

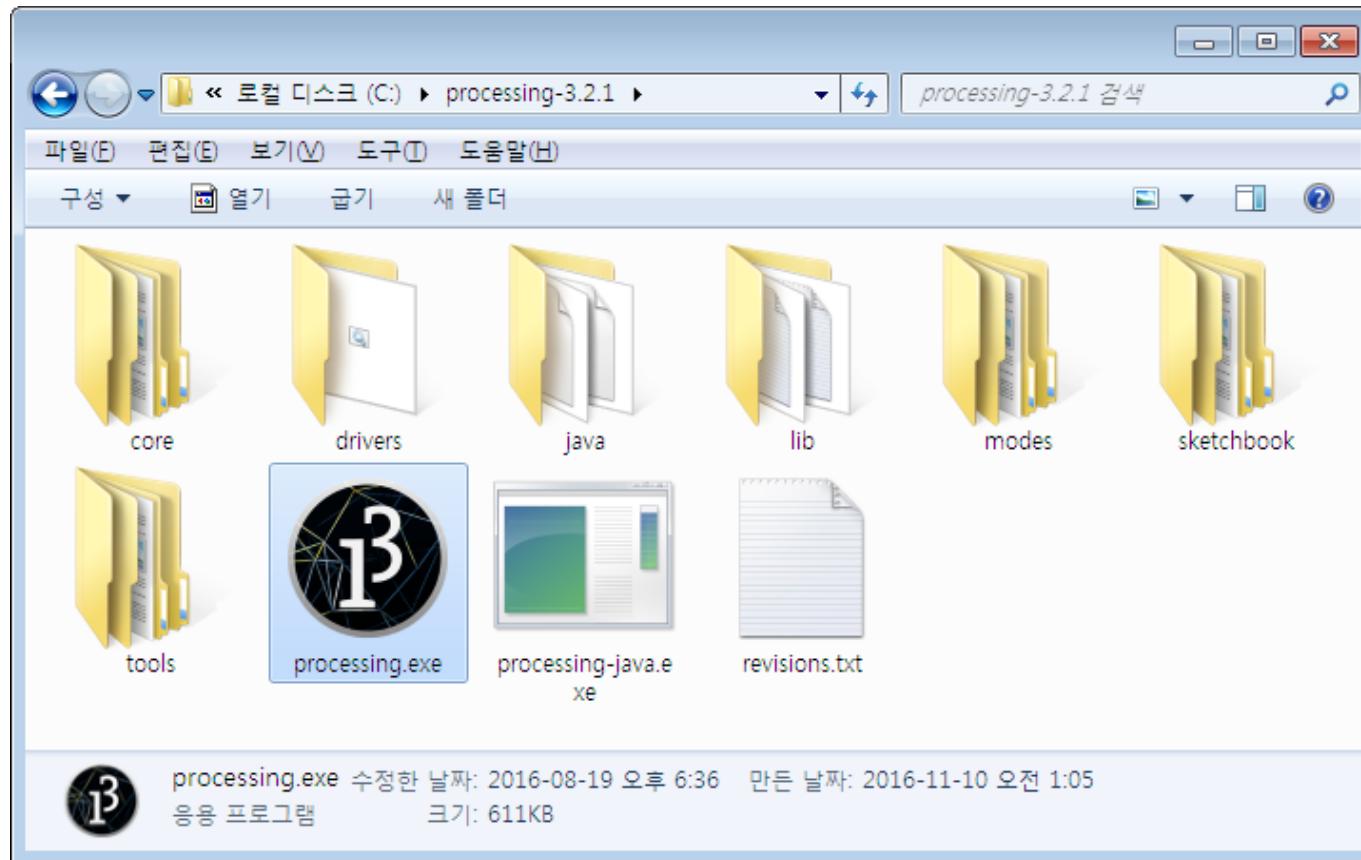
프로세싱

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박광현

프로세싱 실행

2

- C:\processing-3.2.1 폴더

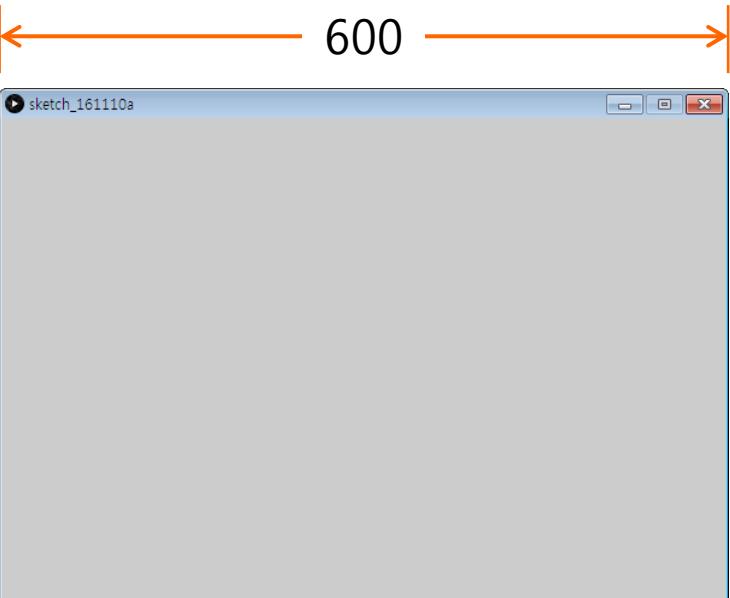


창 나타내기

3

```
size(600, 400);
```

폭 높이



A screenshot of the Processing IDE interface. At the top, there is a blue header bar with the text "실행" (Run) and "정지" (Stop) in Korean. Below the header is a toolbar with icons for file operations. The main workspace shows a sketch titled "sketch_161110a" containing the single line of code: "size(600, 400);". The code editor has a dark background with light-colored text. At the bottom of the screen, there are two tabs: "Console" and "Errors".

```
sketch_161110a | Processing 3.2.1
파일 편집 스케치 Debug 도구 도움말
sketch_161110a
1 size(600, 400);
2
3
4
5
6
7
8
9
10
11
12
13
14
15
16
17
18
19
20
Console Errors
```

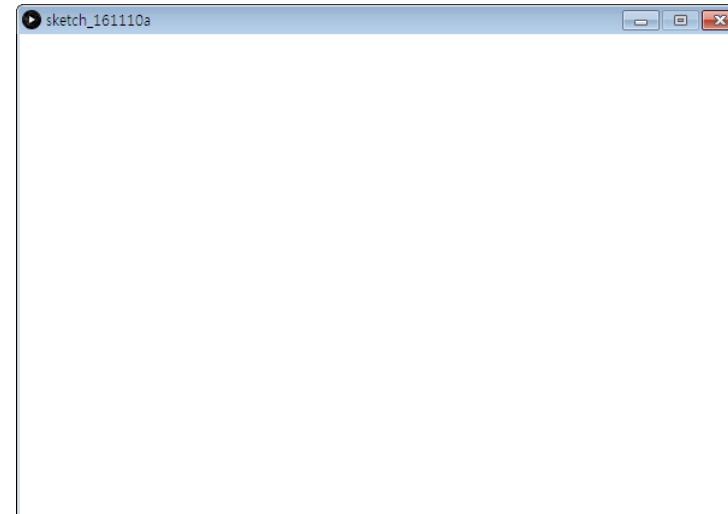
도형 그리기

배경 칠하기

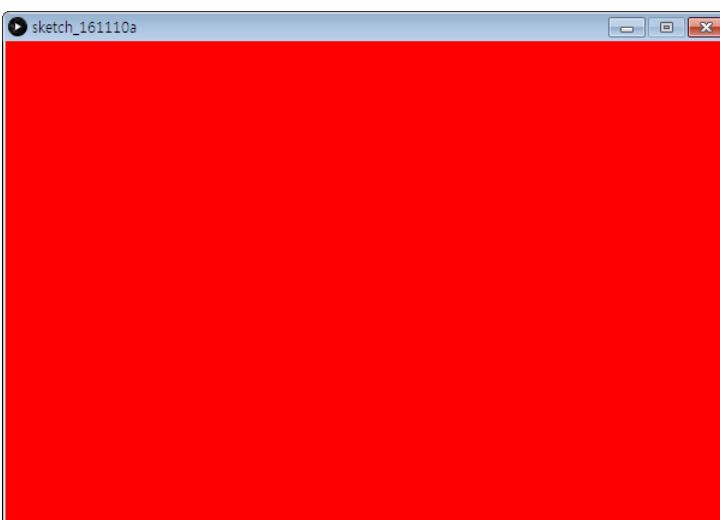
5

```
size(600, 400);  
background(255, 255, 255);
```

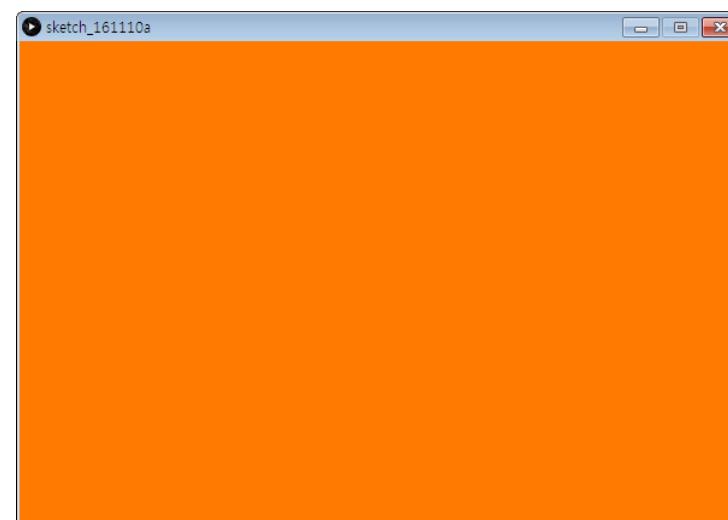
R G B



```
size(600, 400);  
background(255, 0, 0);
```



```
size(600, 400);  
background(255, 122, 0);
```

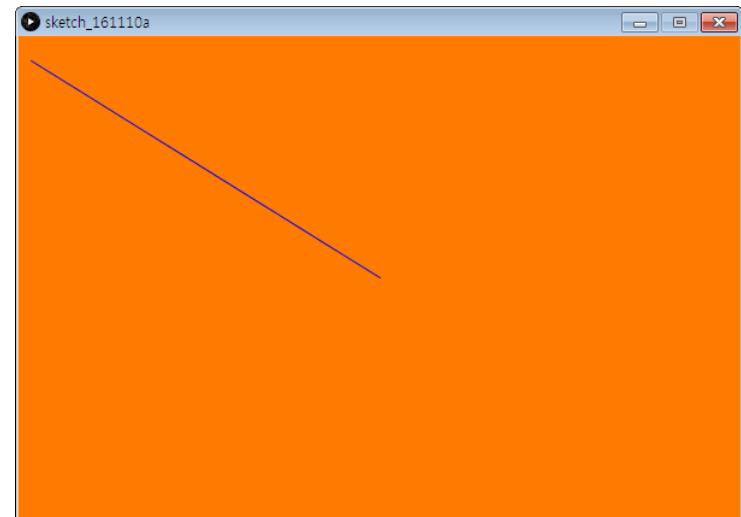
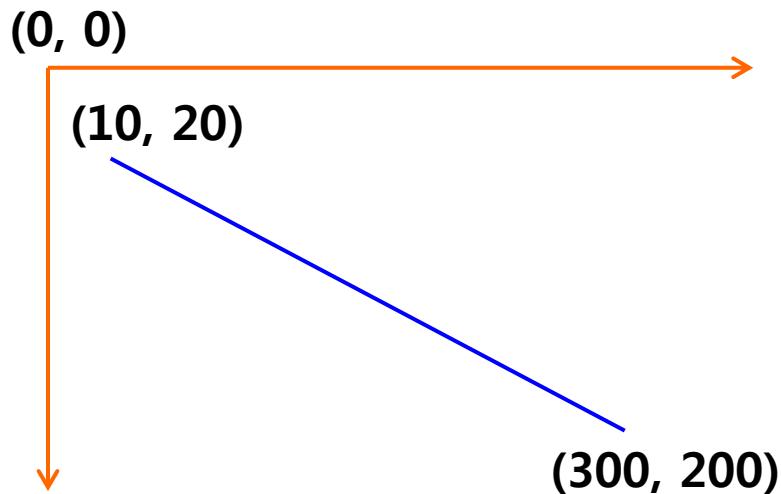


선 그리기

6

```
size(600, 400);
background(255, 122, 0);
stroke(0, 0, 255);
line(10, 20, 300, 200);
```

선 색깔 (그리기 전에 설정한다)

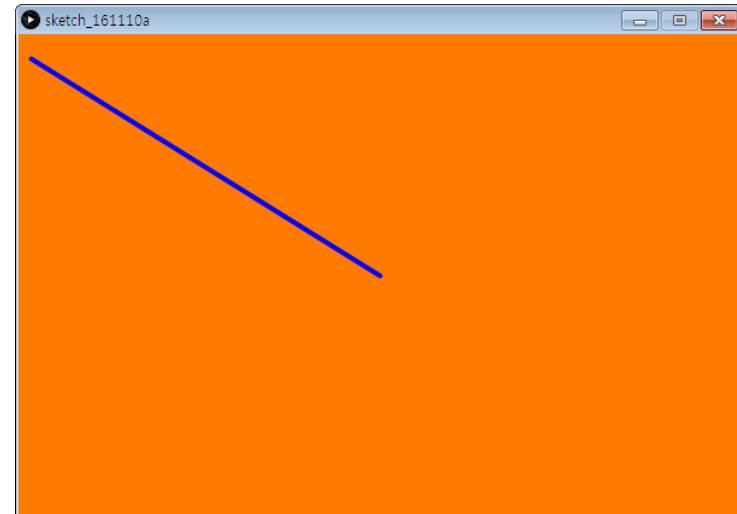


선 두께

7

```
size(600, 400);
background(255, 122, 0);
stroke(0, 0, 255);
strokeWeight(4);
line(10, 20, 300, 200);
```

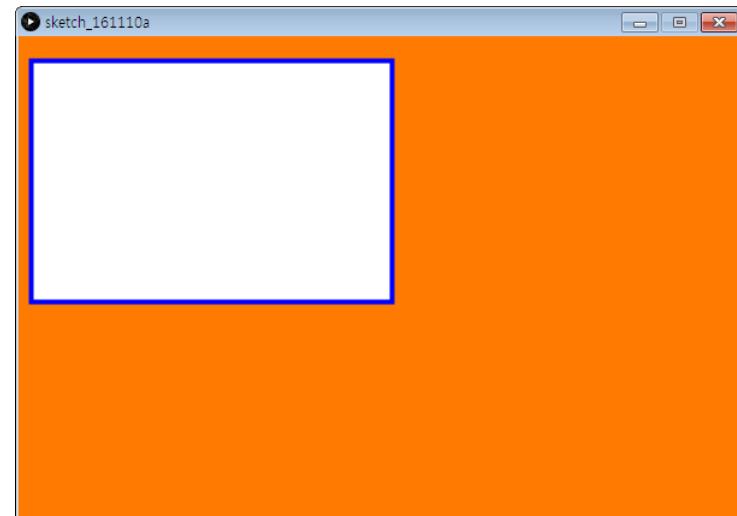
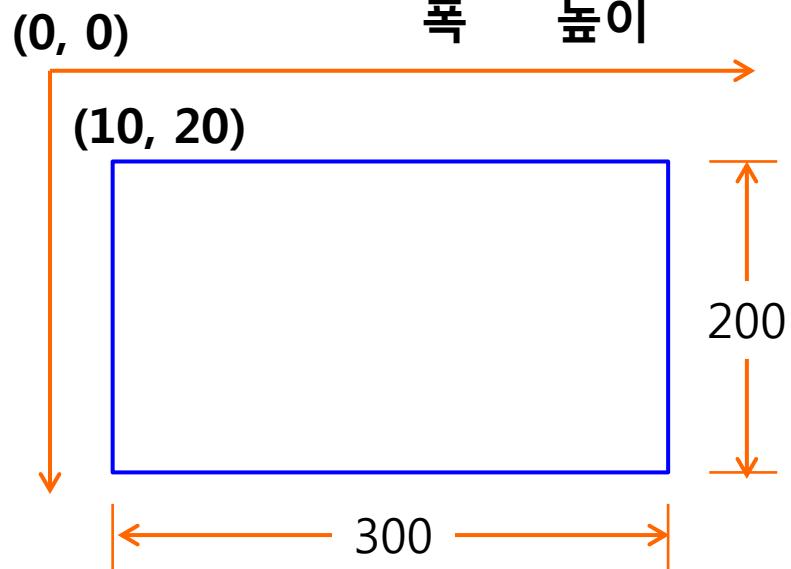
선 두께 (픽셀) (그리기 전에 설정한다)



직사각형 그리기

8

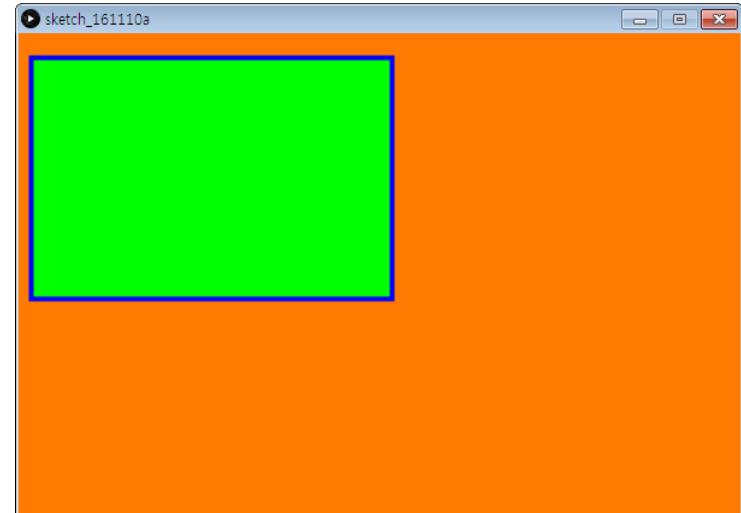
```
size(600, 400);
background(255, 122, 0);
stroke(0, 0, 255);
strokeWeight(4);
rect(10, 20, 300, 200);
```



색깔 채우기

9

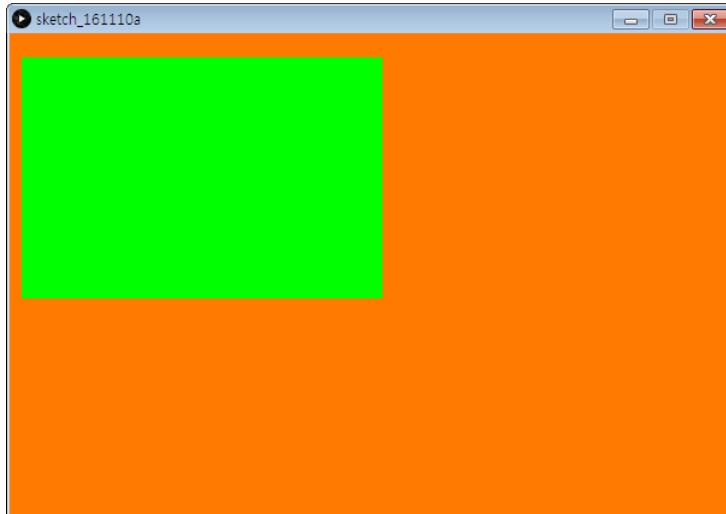
```
size(600, 400);
background(255, 122, 0);
stroke(0, 0, 255);
strokeWeight(4);
fill(0, 255, 0); —————→ 채우기 색깔 (그리기 전에 설정한다)
rect(10, 20, 300, 200);
```



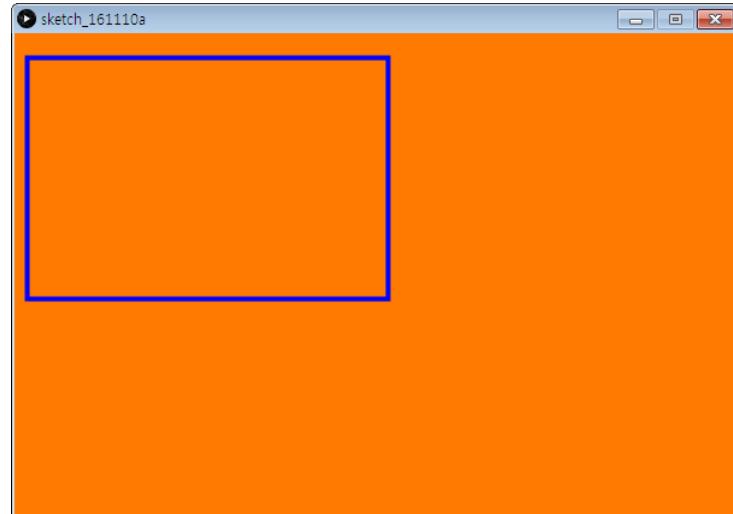
선/채움 없애기

10

```
size(600, 400);
background(255, 122, 0);
stroke(0, 0, 255);
strokeWeight(4);
fill(0, 255, 0);
noStroke();
rect(10, 20, 300, 200);
```



```
size(600, 400);
background(255, 122, 0);
stroke(0, 0, 255);
strokeWeight(4);
fill(0, 255, 0);
noFill();
rect(10, 20, 300, 200);
```

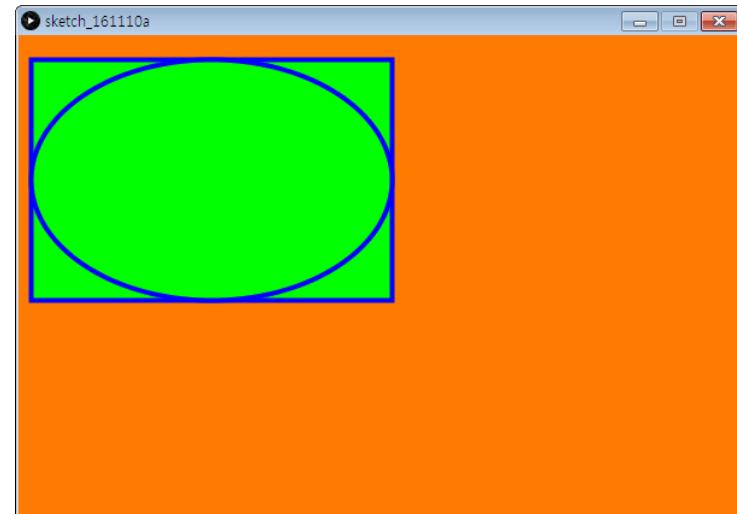
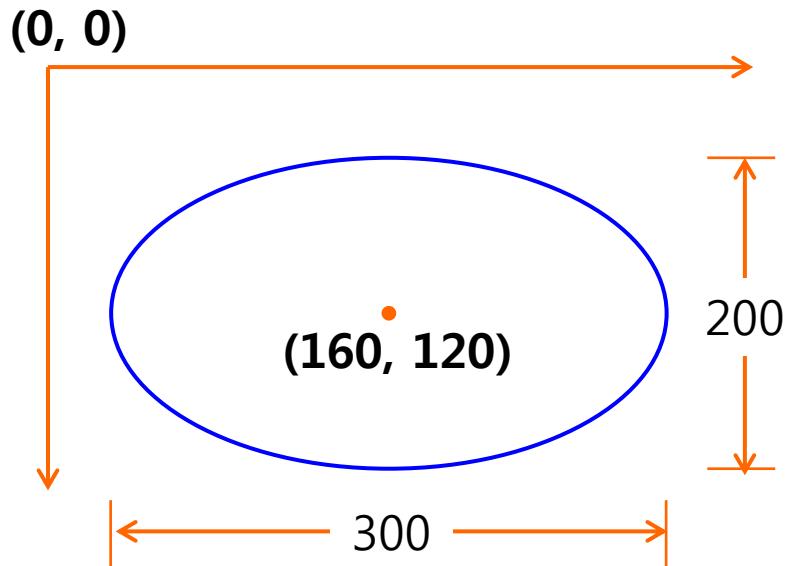


타원 그리기

11

```
size(600, 400);
background(255, 122, 0);
stroke(0, 0, 255);
strokeWeight(4);
fill(0, 255, 0);
rect(10, 20, 300, 200);
ellipse(160, 120, 300, 200);
```

폭 높이

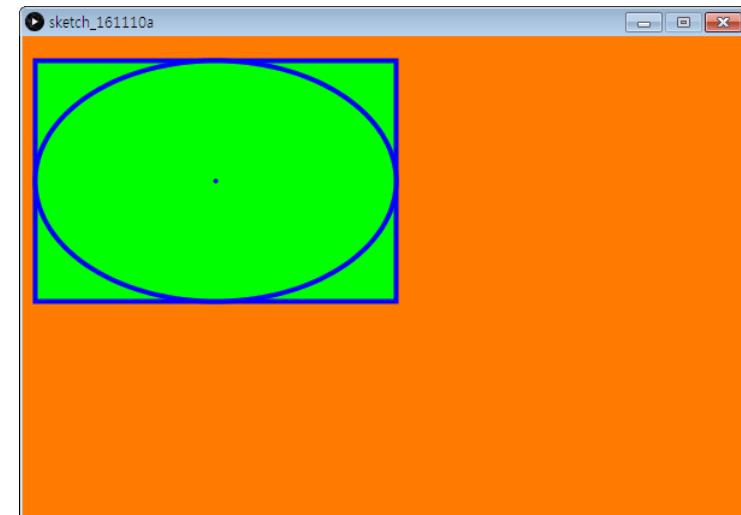
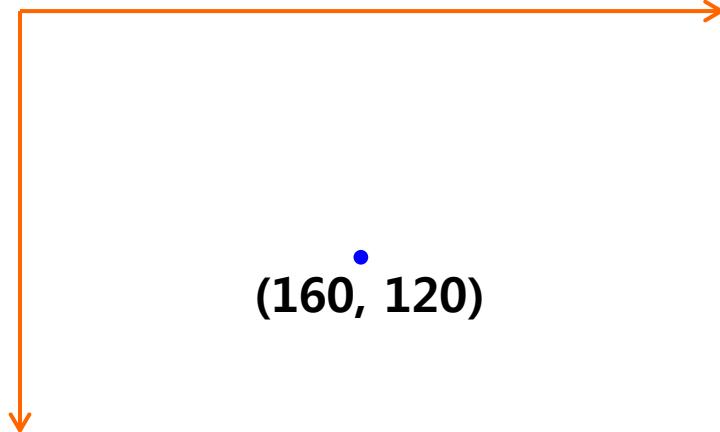


점 그리기

12

```
size(600, 400);
background(255, 122, 0);
stroke(0, 0, 255);
strokeWeight(4);
fill(0, 255, 0);
rect(10, 20, 300, 200);
ellipse(160, 120, 300, 200);
point(160, 120);
```

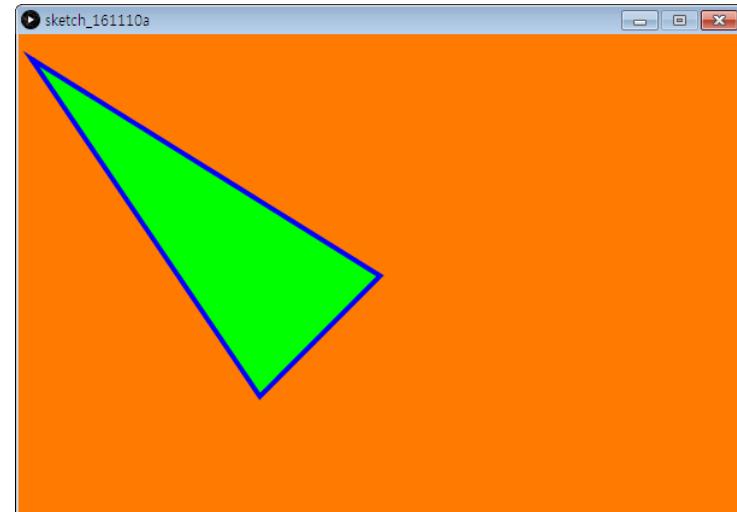
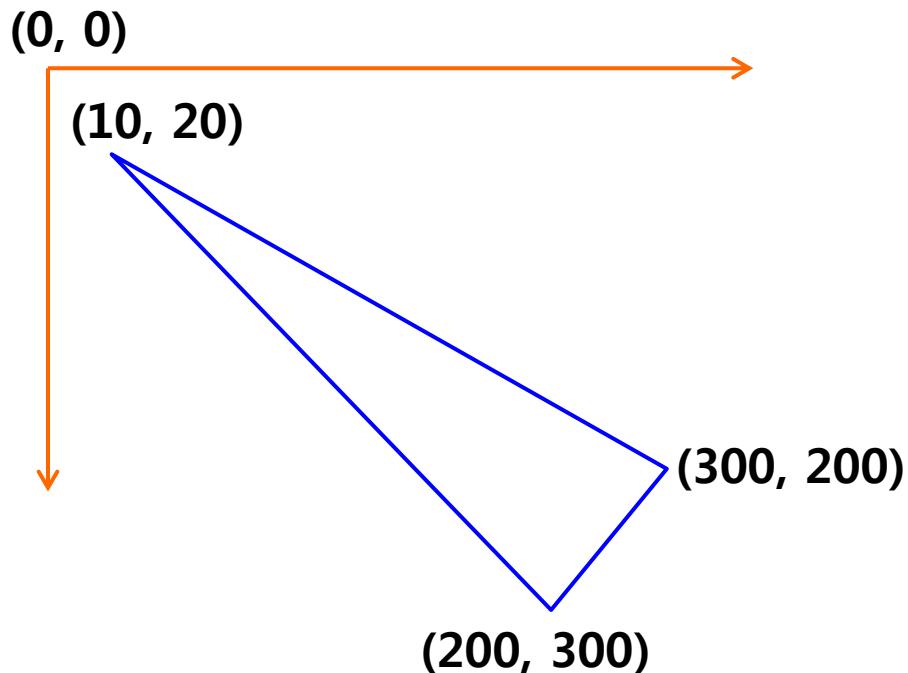
(0, 0)



삼각형 그리기

13

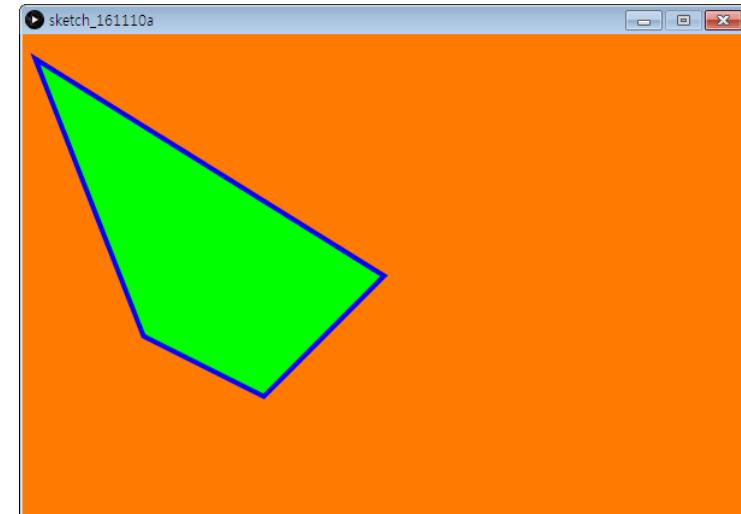
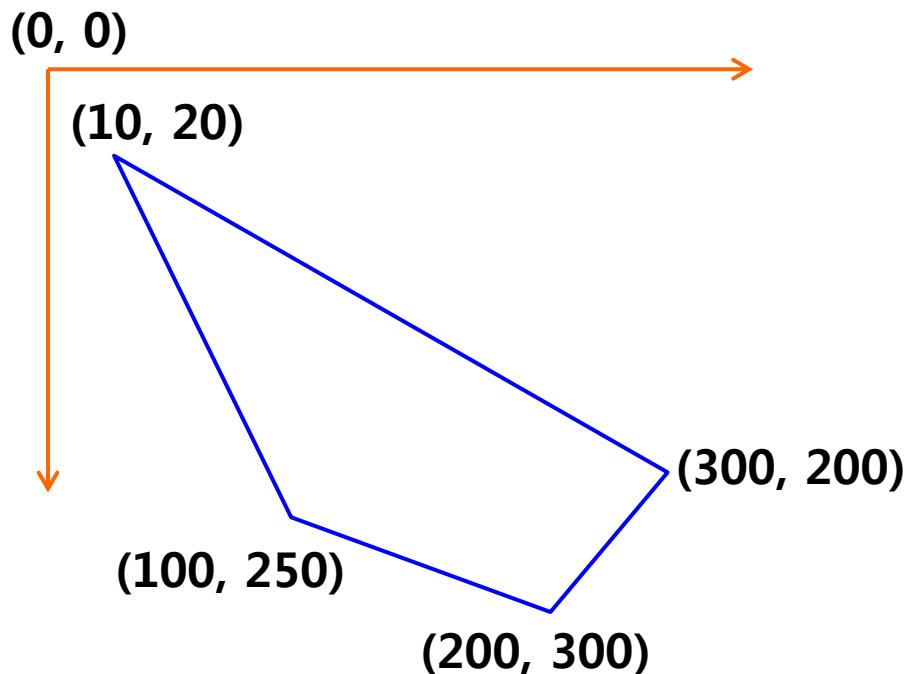
```
size(600, 400);
background(255, 122, 0);
stroke(0, 0, 255);
strokeWeight(4);
fill(0, 255, 0);
triangle(10, 20, 300, 200, 200, 300);
```



사각형 그리기

14

```
size(600, 400);
background(255, 122, 0);
stroke(0, 0, 255);
strokeWeight(4);
fill(0, 255, 0);
quad(10, 20, 300, 200, 200, 300, 100, 250);
```



애니메이션

기본 형태

16

```
void setup() {  
}  
  
void draw() {  
}
```

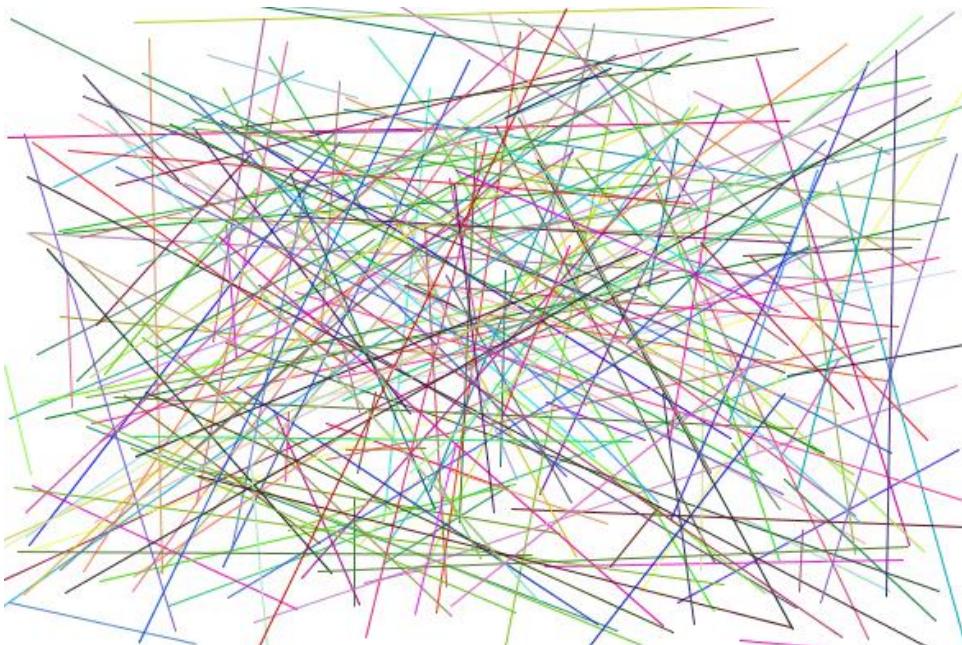
색깔 애니메이션

17

```
void setup() {  
    size(600, 400);  
    background(255, 122, 0);  
    stroke(0, 0, 255);  
}  
  
void draw() {  
    int c = frameCount % 256;  
    fill(c, 0, 0);  
    rect(10, 20, 300, 200);  
}
```

1부터 시작
draw() 호출하고 1씩 증가

```
void setup() {  
    size(600, 400);  
    background(255, 255, 255);  
}  
  
void draw() {  
    stroke(random(256), random(256), random(256));  
    line(random(width), random(height), random(width), random(height));  
}
```



- `random(end);`
- `random(start, end);`

end는 포함 안 됨

마우스

19

```
void setup() {  
    size(600, 400);  
    background(255);  
    stroke(0, 0, 255);  
}  
  
void draw() {  
    line(200, 200, mouseX, mouseY);  
}
```

→ background(255, 255, 255)
와 같음

```
void setup() {  
    size(600, 400);  
    stroke(0, 0, 255);  
}  
  
void draw() {  
    background(255);  
    line(200, 200, mouseX, mouseY);  
}
```

마우스

20

```
void setup() {  
    size(600, 400);  
    stroke(0, 0, 255);  
}  
  
void draw() {  
    line(200, 200, mouseX, mouseY);  
}  
  
void mousePressed() {  
    background(255);  
}
```

```
void setup() {  
    size(600, 400);  
    stroke(0, 0, 255);  
}  
  
void draw() {  
    line(200, 200, mouseX, mouseY);  
}  
  
void mousePressed() {  
    if(mouseButton == LEFT)  
        background(255);  
    else  
        background(255, 122, 0);  
}
```

- `mouseButton`
- `mouseClicked()`
- `mouseDragged()`
- `mouseMoved()`
- `mousePressed()`
- `mouseReleased()`
- `mouseWheel()`
- `mouseX`
- `mouseY`
- `pmouseX`
- `pmouseY`

```
void setup() {  
    size(600, 400);  
    background(255);  
    stroke(0, 0, 255);  
}  
  
void draw() {  
}  
  
void mouseDragged() {  
    line(pmouseX, pmouseY, mouseX, mouseY);  
}
```

마우스

24

```
void setup() {  
    size(600, 400);  
    background(255);  
    stroke(0, 0, 255);  
    fill(0, 255, 0);  
}  
  
void draw() {  
    background(255);  
    rect(mouseX, mouseY, 30, 30);  
}
```

```
void setup() {  
    size(600, 400);  
    background(255);  
    stroke(0, 0, 255);  
}  
  
void draw() {  
    line(200, 200, mouseX, mouseY);  
}  
  
void keyPressed() {  
    if(key == 'a')  
        background(255);  
    else  
        background(255, 122, 0);  
}
```

- **key**
- **keyCode**
- **keyPressed()**
- **keyPressed**
- **keyReleased()**
- **keyTyped()**

햄스터

라이브러리 사용

28

- 스케치
 - > 내부 라이브러리...
 - > Roboid

```
sketch_161110a | Processing 3.2.1
파일 편집 스케치 Debug 도구 도움말
sketch_161110a
1 import org.roboid.core.*;
2 import processing.hamster.*;
3 import org.roboid.robot.*;
4
5
6
7
8
9
10
11
12
13
14
15
16
17
18
19
20
```

Console Errors

1초 앞으로 이동하기

29

```
import org.roboide.core.*;
import processing.hamster.*;
import org.roboide.robot.*;

Hamster hamster;

void setup() {
    hamster = Hamster.create(this);
}

void draw() {
}

void run() {
    hamster.wheels(30, 30);
    delay(1000);
    hamster.stop();
}
```



왼쪽 바퀴 속도 (-100 ~ 100) %

오른쪽 바퀴 속도 (-100 ~ 100) %

msec (1000분의 1초 단위)

1초 뒤로 이동하기

30

```
import org.roboide.core.*;
import processing.hamster.*;
import org.roboide.robot.*;

Hamster hamster;

void setup() {
    hamster = Hamster.create(this);
}

void draw() {
}

void run() {
    hamster.wheels(-30, -30);
    delay(1000);
    hamster.stop();
}
```



제자리 돌기 (스핀)

31

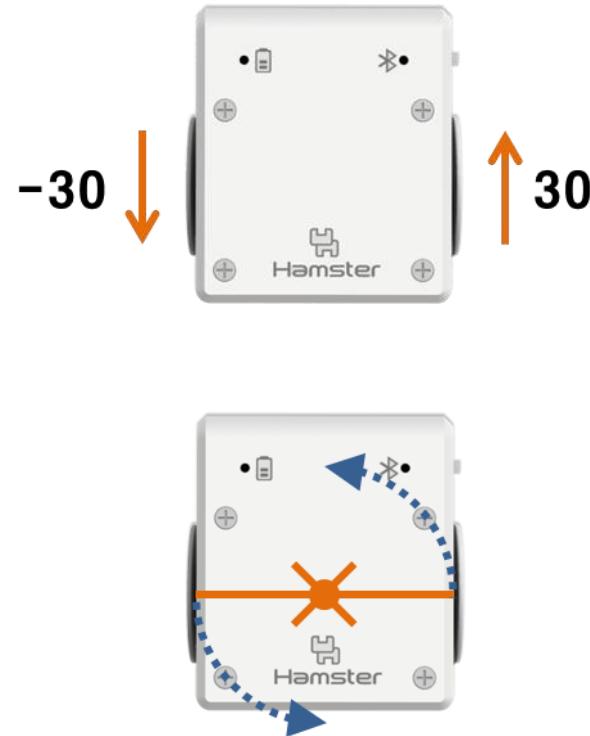
```
import org.roboide.core.*;
import processing.hamster.*;
import org.roboide.robot.*;

Hamster hamster;

void setup() {
    hamster = Hamster.create(this);
}

void draw() {
}

void run() {
    hamster.wheels(-30, 30);
    delay(1000);
    hamster.stop();
}
```



한쪽 바퀴를 축으로 회전하기 (피봇 턴)

32

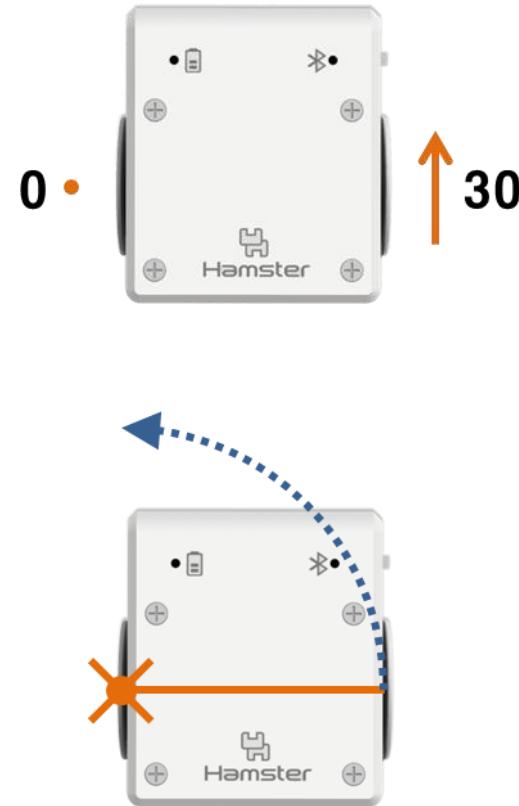
```
import org.roboide.core.*;
import processing.hamster.*;
import org.roboide.robot.*;

Hamster hamster;

void setup() {
    hamster = Hamster.create(this);
}

void draw() {
}

void run() {
    hamster.wheels(0, 30);
    delay(1000);
    hamster.stop();
}
```



둥글게 회전하기 (라운드 턴)

33

```
import org.roboide.core.*;
import processing.hamster.*;
import org.roboide.robot.*;

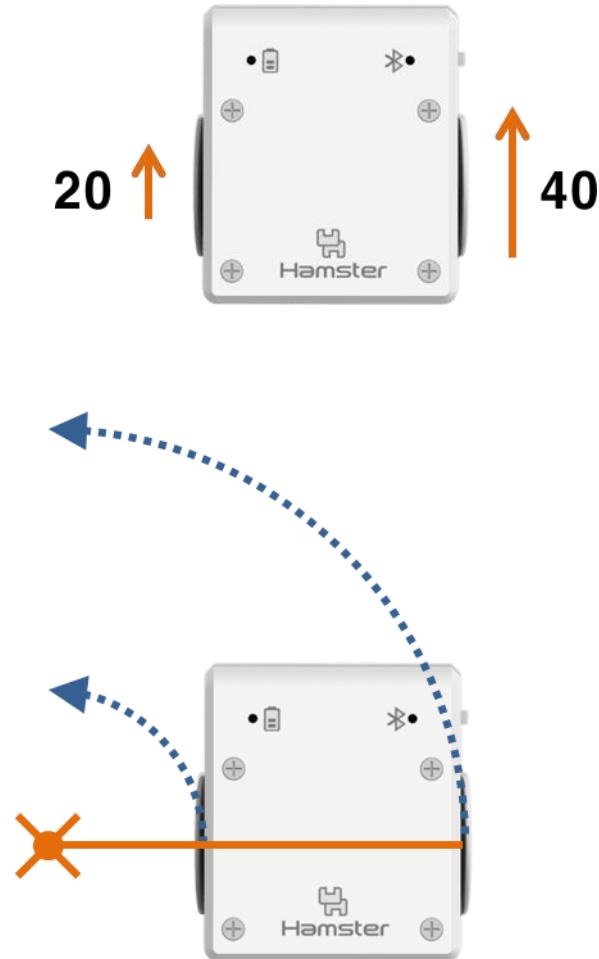
Hamster hamster;

void setup() {
    hamster = Hamster.create(this);
}

void draw() {

}

void run() {
    hamster.wheels(20, 40);
    delay(1000);
    hamster.stop();
}
```



근접 센서 값 관찰하기

34

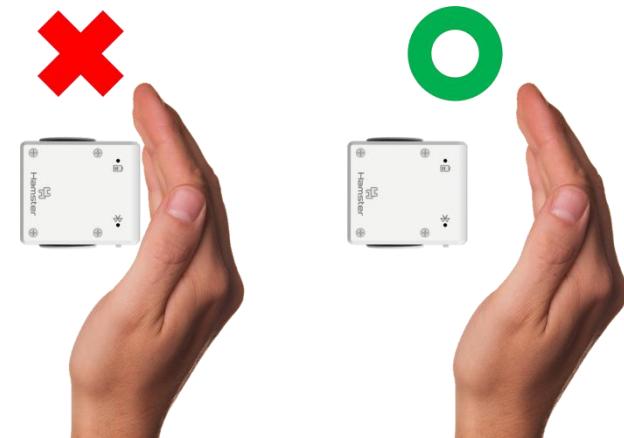
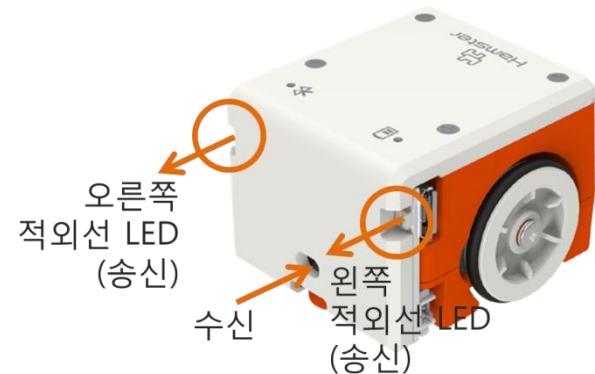
```
import org.roboide.core.*;
import processing.hamster.*;
import org.roboide.robot.*;

Hamster hamster;

void setup() {
    hamster = Hamster.create(this);
}

void draw() {
}

void run() {
    while(true) {
        println(hamster.leftProximity());
        delay(20);
    }
}
```



손을 가져 가면 뒤로 도망가기

35

```
import org.roboid.core.*;
import processing.hamster.*;
import org.roboid.robot.*;

Hamster hamster;

void setup() {
    hamster = Hamster.create(this);
}

void draw() {
}

void run() {
    while(hamster.leftProximity() < 50) {
        delay(20);
    }
    hamster.wheels(-30, -30);
}
```

```
...  
  
void run() {  
    while(true) {  
        if(hamster.leftProximity() > 40) {  
            hamster.wheels(-30, -30);  
        } else {  
            hamster.wheels(30, 30);  
        }  
        delay(20);  
    }  
}
```

LED 켜고 끄기

37

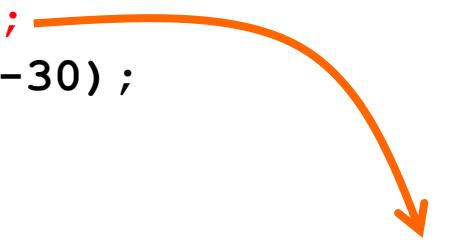
```
...  
  
void run() {  
    while(true) {  
        if(hamster.leftProximity() > 40) {  
            hamster.leds(Hamster.LED_RED, Hamster.LED_RED);  
            hamster.wheels(-30, -30);  
        } else {  
            hamster.leds(0, 0);  
            hamster.wheels(30, 30);  
        }  
        delay(20);  
    }  
}
```

왼쪽 LED 색깔
오른쪽 LED 색깔

버저 소리내기

38

```
...  
  
void run() {  
    while(true) {  
        if(hamster.leftProximity() > 40) {  
            hamster.leds(Hamster.LED_RED, Hamster.LED_RED);  
            hamster.buzzer(1000);  
            hamster.wheels(-30, -30);  
        } else {  
            hamster.leds(0, 0);  
            hamster.buzzer(0);  
            hamster.wheels(30, 30);  
        }  
        delay(20);  
    }  
}
```



Hz

햄스터 + 그래픽

키보드 조종기

40

```
import org.robovm.core.*;
import processing.hamster.*;
import org.robovm.robot.*;

Hamster hamster;

void setup() {
    hamster = Hamster.create(this);
}

void draw() {
```

```
void keyPressed() {
    if(key == ' ')
        hamster.stop();
    else if(key == CODED) {
        if(keyCode == UP)
            hamster.wheels(30, 30);
        else if(keyCode == DOWN)
            hamster.wheels(-30, -30);
        else if(keyCode == LEFT)
            hamster.wheels(-30, 30);
        else if(keyCode == RIGHT)
            hamster.wheels(30, -30);
    }
}
```

마우스 조종기

41

```
import org.robooid.core.*;
import processing.hamster.*;
import org.robooid.robot.*;

Hamster hamster;

void setup() {
    size(200,200);
    hamster = Hamster.create(this);
}

void draw() {
    background(255);
    fill(0);
    ellipse(100,100, 30, 30);
    line(100 ,100, mouseX, mouseY);
}
```

```
void run() {
    while(true) {
        if(mousePressed) {
            int dx = (100 - mouseX) / 2;
            int dy = (100 - mouseY) / 2;

            if(dy < 0)
                hamster.wheels(dy + dx, dy - dx);
            else
                hamster.wheels(dy - dx, dy + dx);
        } else {
            hamster.stop();
        }
        delay(20);
    }
}
```

수고하셨습니다.

<http://hamster.school>

akaii@kw.ac.kr